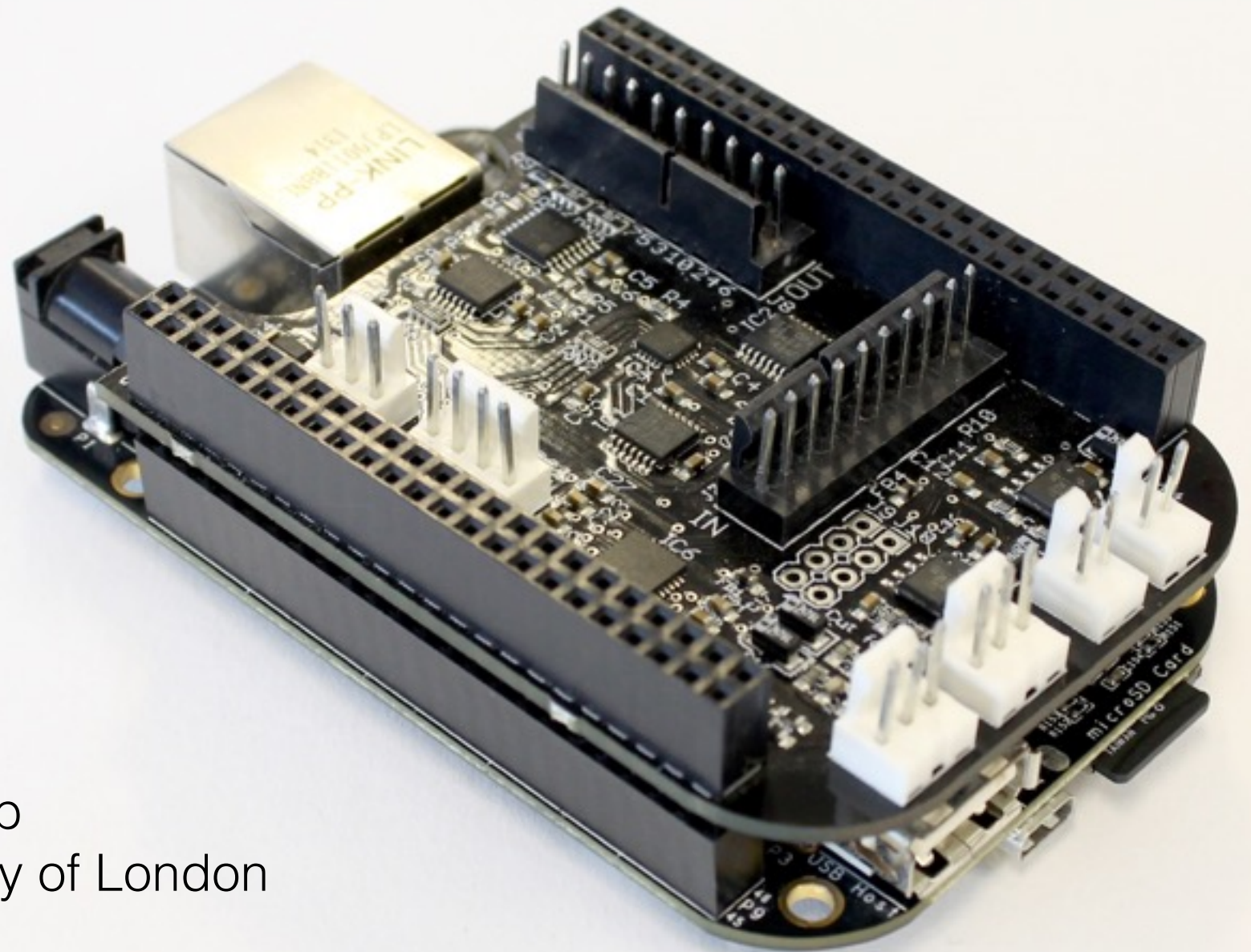


bela

*Ultra-low latency audio and
sensor processing
on the BeagleBone Black*



A project by
The Augmented Instruments Lab
at C4DM, Queen Mary University of London

<http://bela.io>

How it started

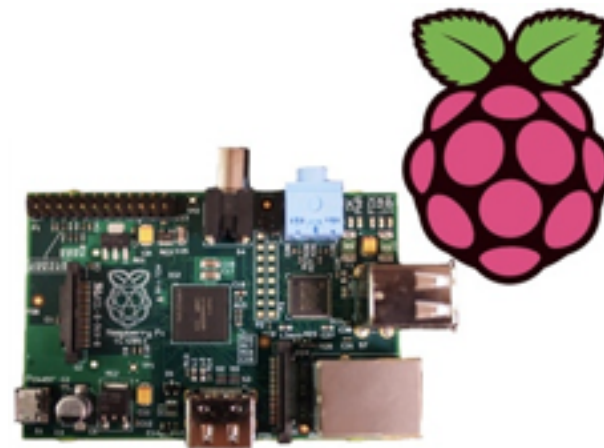
The Goal:

High-performance, self-contained
audio and sensor processing

Already available platforms:



- Easy low-level hardware connectivity
- No OS = precise control of timing
- Very limited CPU (8-bit, 16MHz)
- Not good for audio processing



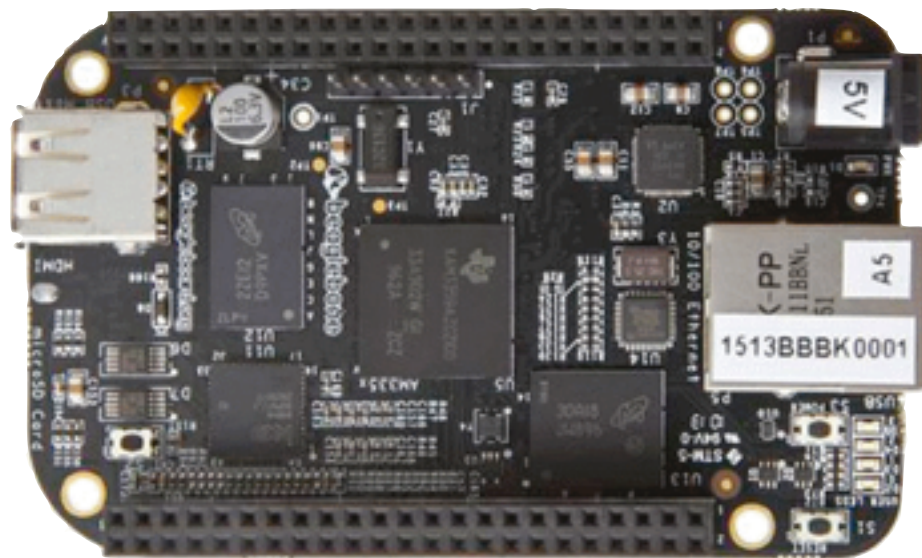
- Reasonable CPU (up to 1GHz ARM)
- High-level hardware (USB, network etc.)
- Limited low-level hardware
- Linux OS = high-latency / underruns



- Fast CPU
- High-level hardware (USB, network etc.)
- Arduino for low-level
- USB connection = high-latency, jitter
- Bulky, not self-contained

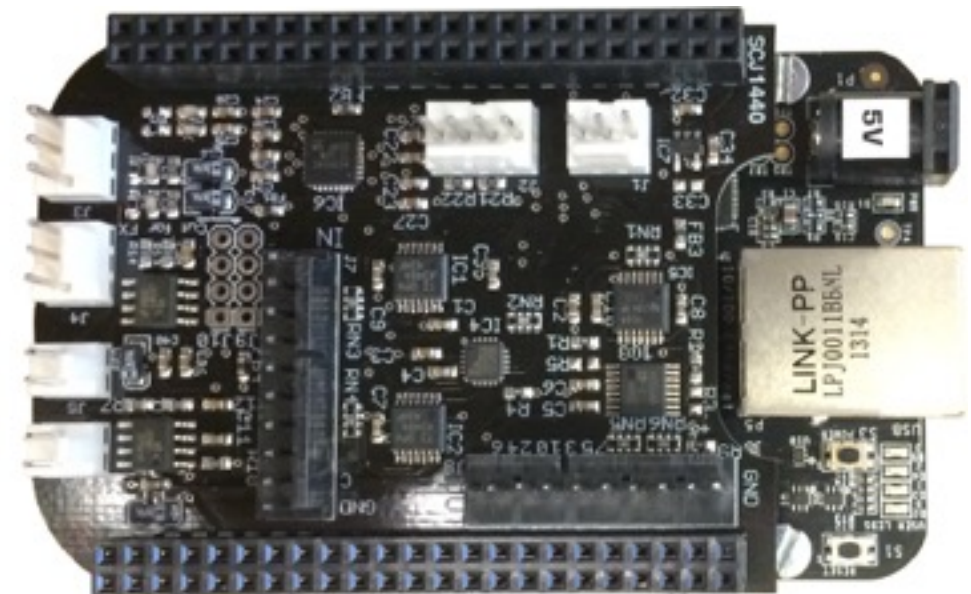
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Hardware



BeagleBone Black

1GHz ARM Cortex-A8
NEON vector floating point
PRU real-time microcontrollers
512MB RAM



Custom Bela Cape

Stereo audio in + out
Stereo 1.1W speaker amps
8x 16-bit analog in + out
16x digital in/out



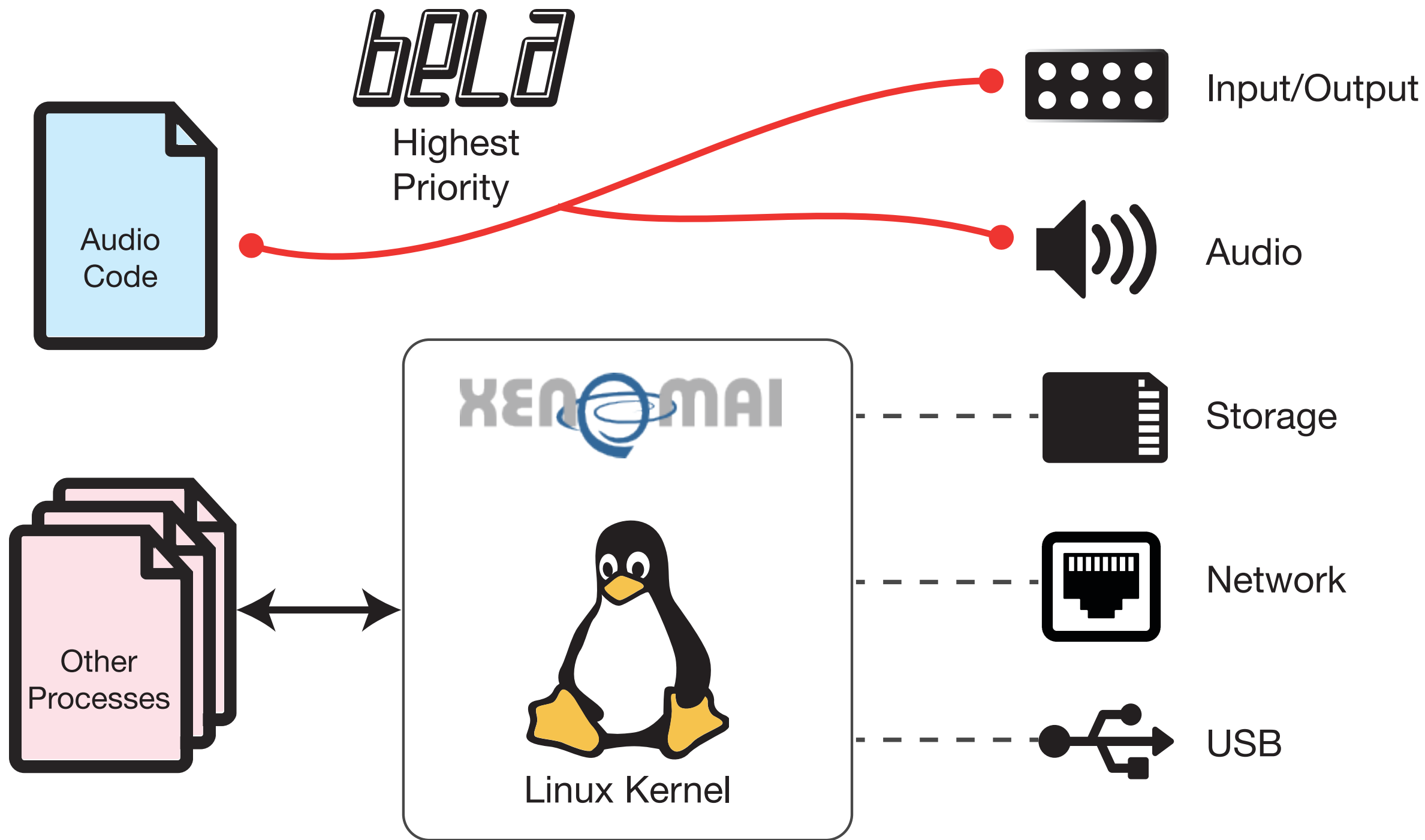
hELd

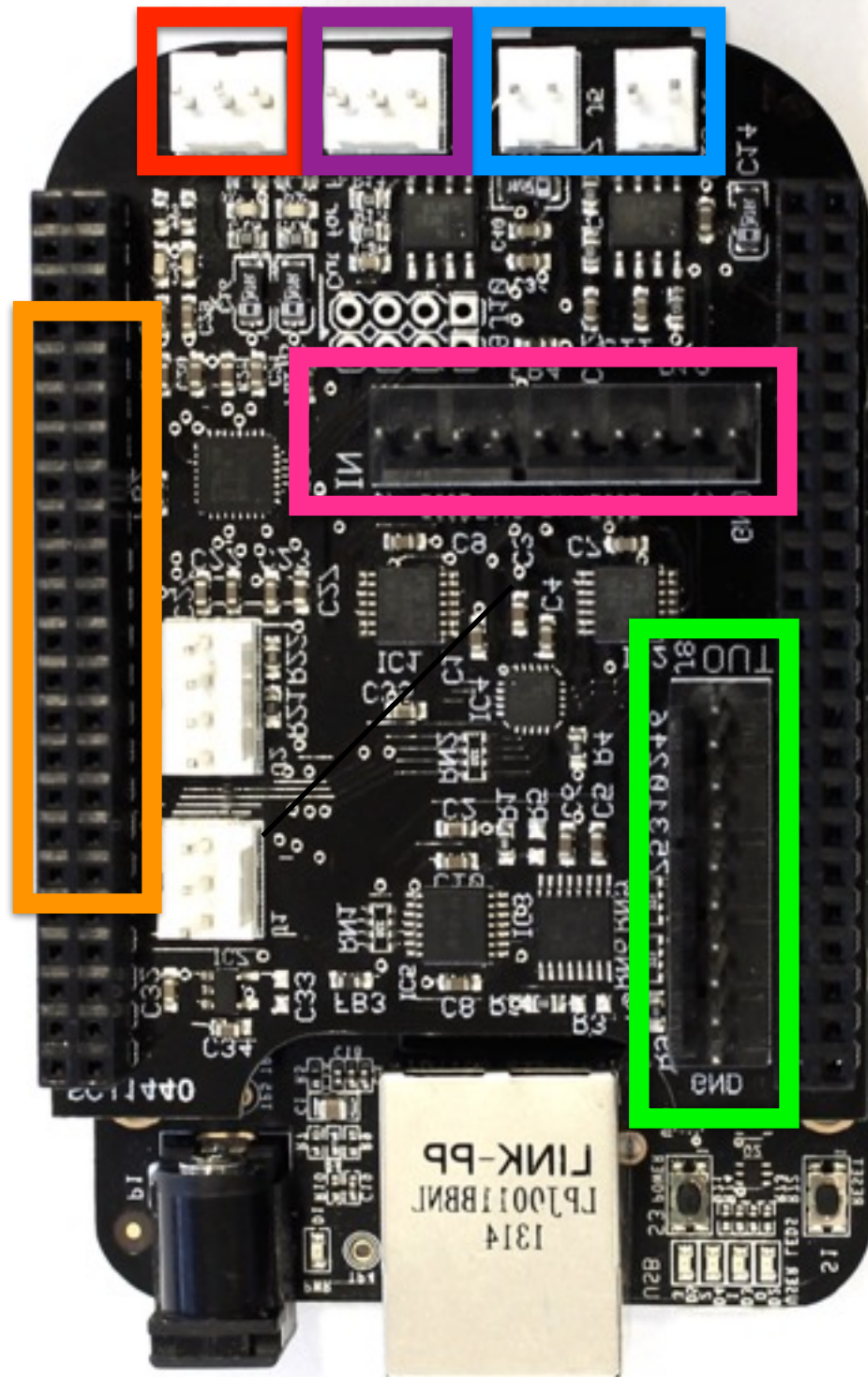


Features

- **1ms round-trip audio latency** without underruns
- **High sensor bandwidth:** digital I/Os sampled at 44.1kHz; analog I/Os sampled at 22.05kHz
- **Jitter-free alignment** between audio and sensors
- **Hard real-time audio+sensor performance**, but full Linux APIs still available
- Programmable using **C/C++, Pd and Faust**
- Designed for **musical instruments and live audio**

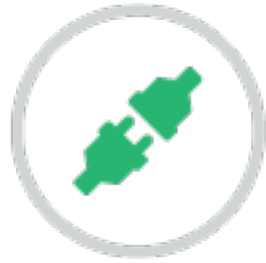
How it works





- **Speakers** with on-board amps
- **Audio In**
- **Audio Out**
- **16x digital I/O**
- **8x 16-bit analogue in (22.05kHz)**
- **8x 16-bit analogue out (22.05kHz)**

Find an interactive pin out diagram at <http://bela.io/belaDiagram>



Connected.



Embedded.



Fast.



Easy to get started.

Getting Started

bela.io/code/wiki

Materials

1. **BeagleBone Black** (BBB)
2. **Bela Cape**
3. **SD card** with Bela image
4. 3.5mm headphone jack **adapter cable**
5. **Mini-USB cable** (to attach BBB to computer)
6. Also useful for hardware hacking: **breadboard**, **jumper wires**, etc.

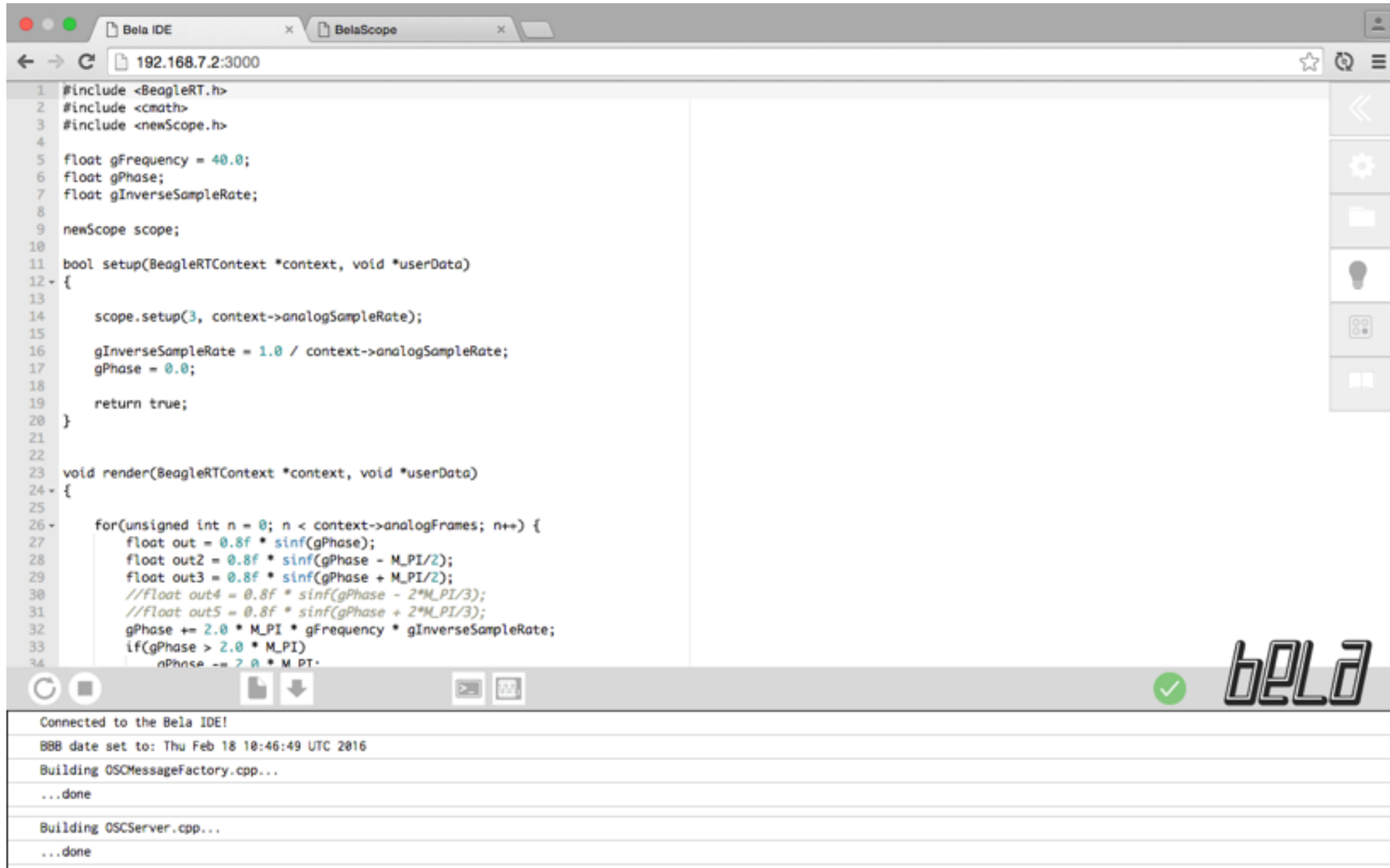
Step 1

Install BBB drivers

Get and install the BeagleBone Black drivers for your operating system:

<http://bela.io/code/wiki> --> Getting Started

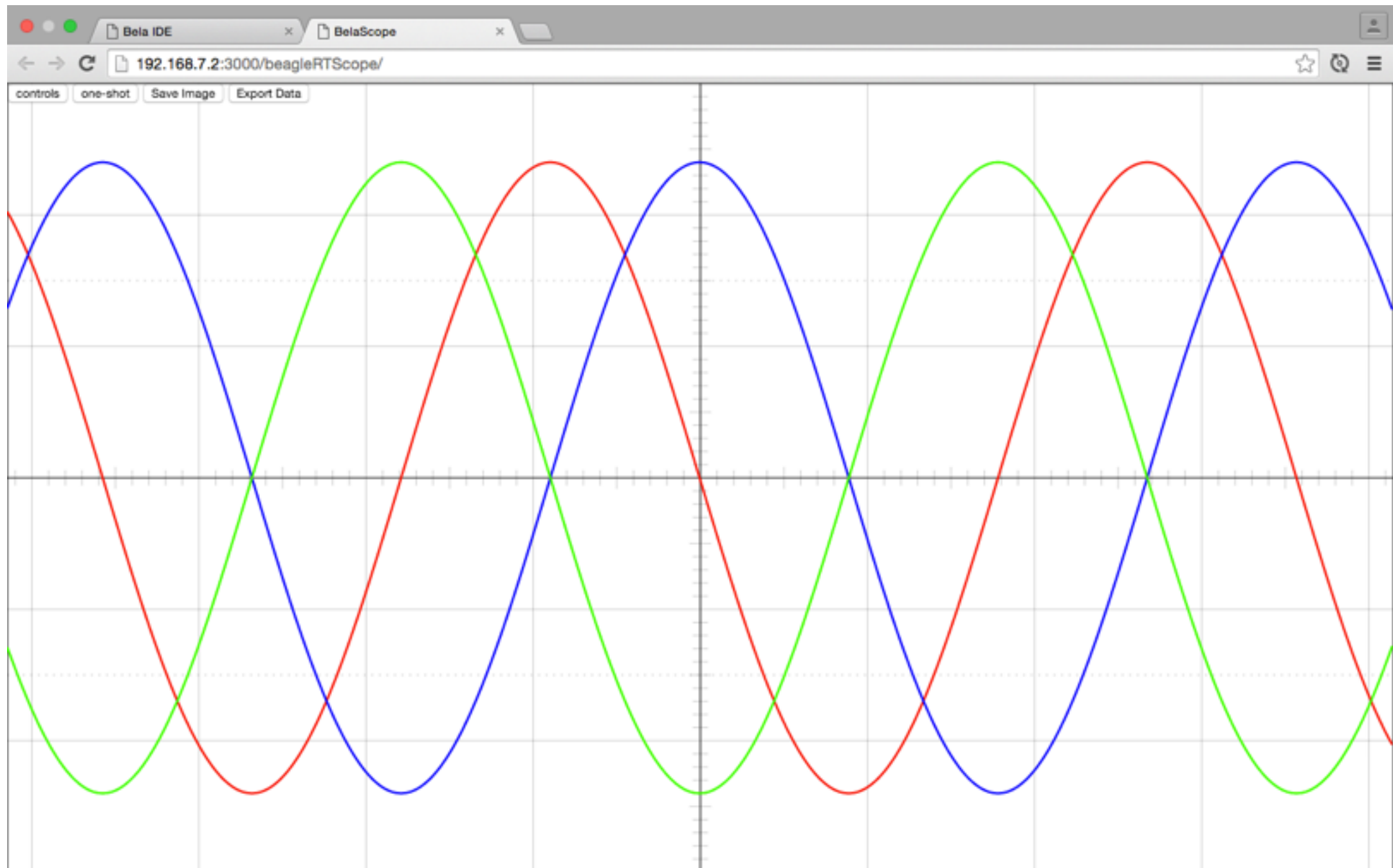
Access the IDE:
<http://192.168.7.2:3000>



```
1 #include <BeagleRT.h>
2 #include <cmath>
3 #include <newScope.h>
4
5 float gFrequency = 40.0;
6 float gPhase;
7 float gInverseSampleRate;
8
9 newScope scope;
10
11 bool setup(BeagleRTContext *context, void *userData)
12 {
13     scope.setup(3, context->analogSampleRate);
14
15     gInverseSampleRate = 1.0 / context->analogSampleRate;
16     gPhase = 0.0;
17
18     return true;
19 }
20
21
22
23 void render(BeagleRTContext *context, void *userData)
24 {
25     for(unsigned int n = 0; n < context->analogFrames; n++) {
26         float out = 0.8f * sinf(gPhase);
27         float out2 = 0.8f * sinf(gPhase - M_PI/2);
28         float out3 = 0.8f * sinf(gPhase + M_PI/2);
29         //float out4 = 0.8f * sinf(gPhase - 2*M_PI/3);
30         //float out5 = 0.8f * sinf(gPhase + 2*M_PI/3);
31         gPhase += 2.0 * M_PI * gFrequency * gInverseSampleRate;
32         if(gPhase > 2.0 * M_PI)
33             gPhase -= 2.0 * M_PI;
34     }
```

Connected to the Bela IDE!
BBB date set to: Thu Feb 18 10:46:49 UTC 2016
Building OSCMessageFactory.cpp...
...done
Building OSCServer.cpp...
...done

Access the IDE:
<http://192.168.7.2:3000>



API introduction

- In `render.cpp`....
- Three main functions:
- `setup()`
runs once at the beginning, before audio starts
gives channel and sample rate info
- `render()`
called repeatedly by Bela system ("callback")
passes input and output buffers for audio and sensors
- `cleanup()`
runs once at end
release any resources you have used
- bela.io/code/embedded *Code docs*

Step 2

How to build other projects

1. **Web interface:** <http://192.168.7.2:3000>
Edit and compile code on the board
2. **Building scripts:**
 1. **Heavy Pd-to-C compiler** (<https://enzienaudio.com>)
Make audio patches in Pd-vanilla, translate to C and compile on board
 2. **Libpd**
Compile Pd patches without Heavy - access to more objects but not as fast, but good for prototyping
 3. **Faust**
Build online, export to C++, run on Bela

Bela and PureData

Heavy	libpd
Proprietary compiler, cloud-based, MIT non-commercial code	Free
Targets a variety of platforms (C, js, Unity, VST2)	Many ports (ofxpd, webpd ...)
Requires internet connection and local compiling (~1minute)	Instantaneous (save the pd patch and restart)
Generates fast, optimized code, uses little CPU	It is just Pd (...)

libpd on Bela

How to run PureData patches on Bela with libpd :

1. Go to <http://bela.io/code/files> and download the bela-ableton-2016-04-12.zip archive
2. Unzip the archive into a convenient location and open a terminal window
3. Navigate into the scripts/ folder and run
`./run_pd_libpd.sh` `../projects/heavy/pd/demo-track/`
4. Type "yes" and you should hear something

Bela and Faust

- Today: you will have to download the C++ file generated by the <http://faust.grame.fr/onlinecompiler/> (after setting the -i flag), save it on your computer and target it with the build_project.sh script, as in:

```
/path/to/bela/repo/scripts/build_project.sh /path/to/faust/file/CppCode.cpp
```

```
freq = hslider("[1]Frequency[BELA:ANALOG_0]",  
440,460,1500,1):smooth(0.999);  
pressure = hslider("[2]Pressure[style:knob][BELA:ANALOG_4]", 0.96, 0.2,  
2.0, 0.01):smooth(0.999):min(0.99):max(0.2);  
gate = hslider("[0]ON/OFF (ASR Envelope)[BELA:DIGITAL_0]",0,0,1,1);
```


Help me with Supercollider

- We got it to work, thank to Dan Stowell at C4DM
- We run 120sinewaves for 55% CPU time.
- Can you make something more useful with it?

Interested to pre-order a kit?

65£ for a cape + SD card

Delivery: July

<http://bit.ly/1eKffsL>

Stay tuned! Join the announcement list at

<http://bela.io>

Join the discussion list at

<http://lists.bela.io/pipermail/discussion-bela.io/>

Connect a Potentiometer

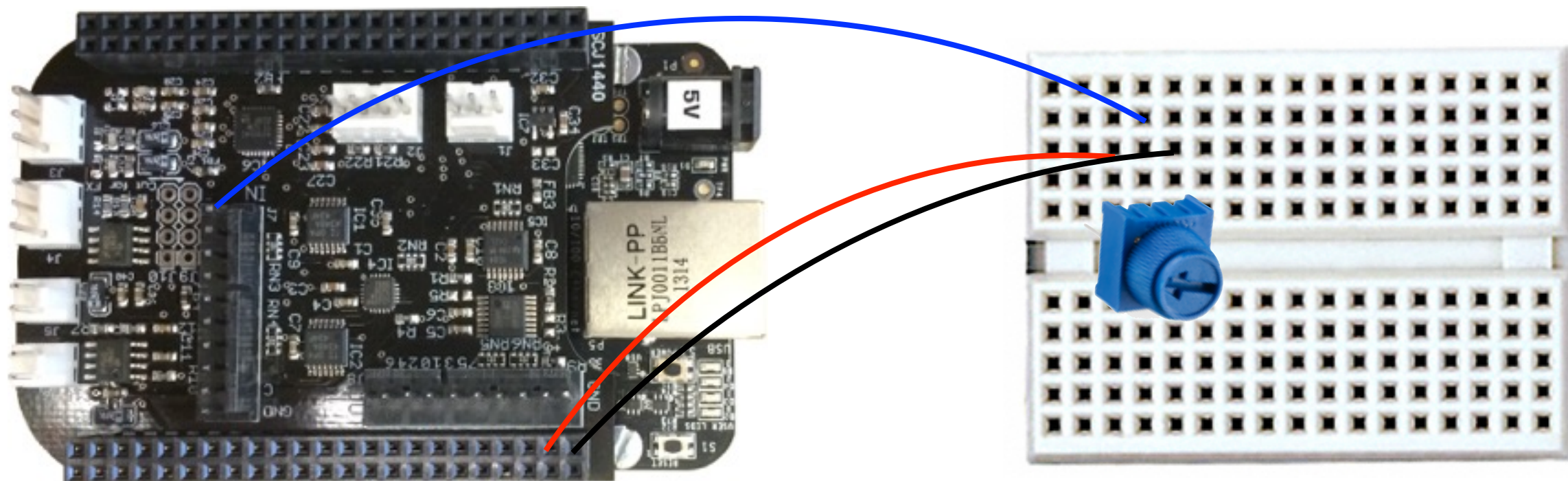
a.k.a. a “pot” or knob

The pot has 3 pins

5V and GND on the outside

Bela **analog in** in the middle

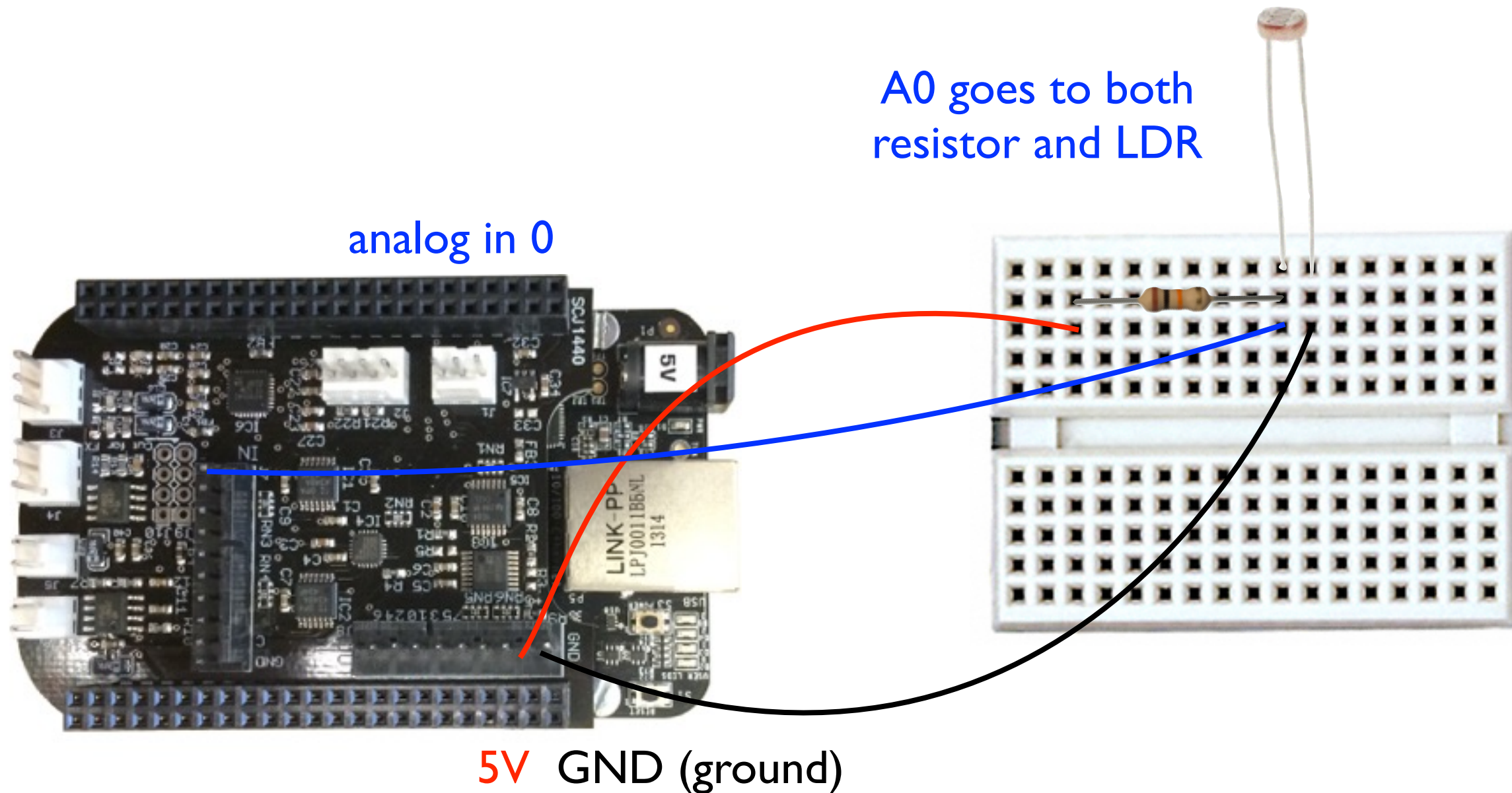
analog in 0



5V GND (ground)

Connect a LDR/FSR*

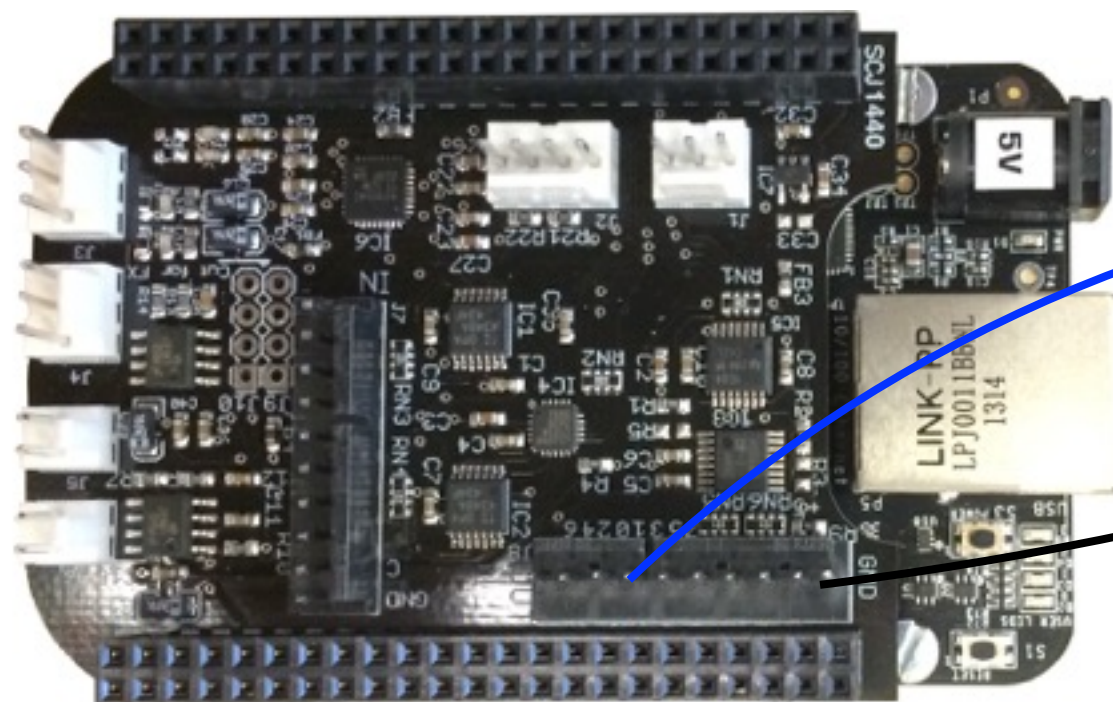
* Light-Dependent Resistor / Force-Sensing Resistor



Connect an LED*

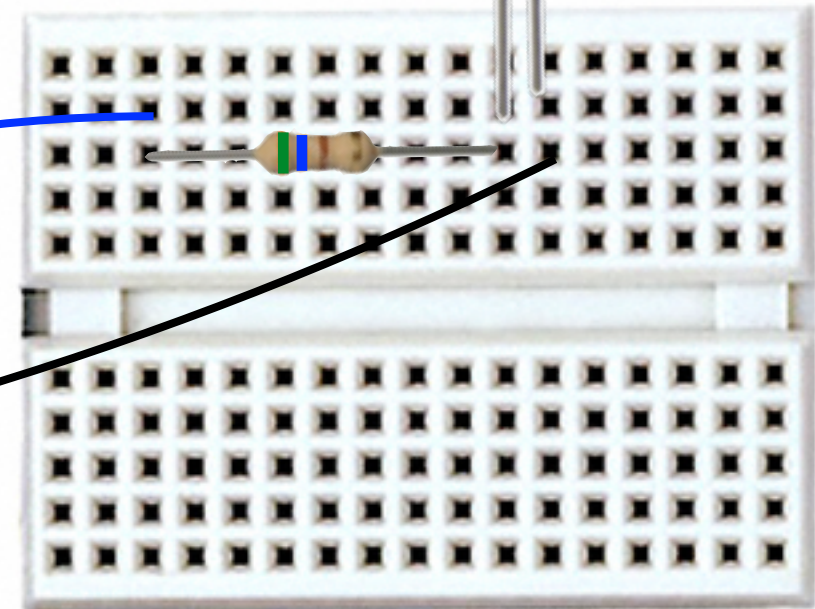
* Light-Emitting Diode

analog out 0
(note pinout:
6 4 2 0 1 3 5 7)



GND (ground)

560 Ω
resistor



Long lead goes
to the resistor

Analog input

```
float gPhase;
float gInverseSampleRate;          /* Pre-calculated for convenience */
int gAudioFramesPerAnalogFrame;

extern int gSensorInputFrequency;  /* Which analog pin controls frequency */
extern int gSensorInputAmplitude;  /* Which analog pin controls amplitude */

void render(BeagleRTContext *context, void *userData)
{
    float frequency = 440.0;
    float amplitude = 0.8;

    for(unsigned int n = 0; n < context->audioFrames; n++) {
        /* There are twice as many audio frames as matrix frames since
           audio sample rate is twice as high */
        if(!(n % gAudioFramesPerAnalogFrame)) {
            /* Every other audio sample: update frequency and amplitude */
            frequency = map(analogReadFrame(context,
                                             n/gAudioFramesPerAnalogFrame,
                                             gSensorInputFrequency),
                           0, 1, 100, 1000);
            amplitude = analogReadFrame(context,
                                         n/gAudioFramesPerAnalogFrame,
                                         gSensorInputAmplitude);
        }

        float out = amplitude * sinf(gPhase);

        for(unsigned int channel = 0; channel < context->audioChannels; channel++)
            context->audioOut[n * context->audioChannels + channel] = out;

        gPhase += 2.0 * M_PI * frequency * gInverseSampleRate;
        if(gPhase > 2.0 * M_PI)
            gPhase -= 2.0 * M_PI;
    }
}
```

This runs **every other sample**

Read the **analog input** at the specified **frame**

Map the 0-1 input range to a frequency range

Digital I/O

```
void render(BeagleRTContext *context, void *userData)
{
    static int count = 0; // counts elapsed samples
    float interval = 0.5; // how often to toggle the LED (in seconds)
    static int status = GPIO_LOW;

    for(unsigned int n = 0; n < context->digitalFrames; n++) {
        /* Check if enough samples have elapsed that it's time to
           blink to the LED */
        if(count == context->digitalSampleRate * interval) {
            count = 0; // reset the counter
            if(status == GPIO_LOW) {
                /* Toggle the LED */
                digitalWriteFrame(context, n, P8_07, status);
                status = GPIO_HIGH;
            }
            else {
                /* Toggle the LED */
                digitalWriteFrame(context, n, P8_07, status);
                status = GPIO_LOW;
            }
        }

        /* Increment the count once per frame */
        count++;
    }
}
```

This runs **once**
per digital frame

Write the **digital**
output at the
specified **frame**

Bela and Heavy

- https://docs.google.com/presentation/d/1DLCDUgZp0liaQhnO55uhOJ5iymbNMmDqPC_JyfTkAaE/
- Nice URL, uh?

bela

Stay tuned! Join the announcement list at

<http://bela.io>

Xenomai remarks

- scheduler can preempt non-preemptable kernel operations
- audio-thread can be set at a higher priority than the Kernel
- mode switches into kernel mode need to be avoided in the audio thread:
 - ▶ disk I/O
 - ▶ socket
 - ▶ printf
 - ▶ pthread
 - ▶ `available.notify_one()`; triggers a mode switch